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# **Inline terminal: 8 digital inputs**

## **ILT 24 DO8/HD /**

## **IB IL 24 DO8/HD-PAC**

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### **Device description**



This manual is intended to provide support for installation and usage of the device. The information is believed to be accurate and reliable. However, SysMik GmbH Dresden assumes no responsibility for possible mistakes and deviations in the technical specifications. SysMik GmbH Dresden reserves the right to make modifications in the interest of technical progress to improve our modules and software or to correct mistakes.

We are grateful to you for criticism and suggestions. Further information (device description, available software) can be found on our homepage [www.sysmik.de](http://www.sysmik.de). Please ask for latest information.

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## Contents

<b>Device description</b>	<b>1</b>
<b>Contents</b>	<b>2</b>
<b>1 Description</b>	<b>4</b>
<b>2 Order information</b>	<b>4</b>
<b>3 Technical data</b>	<b>5</b>
<b>4 Local diagnostic and status indicators and terminal point assignment</b>	<b>8</b>
<b>5 Internal circuit</b>	<b>9</b>
<b>6 Connection notes and examples</b>	<b>10</b>
<b>7 Application examples</b>	<b>11</b>

## 1 Description



**Note:** This device description is only valid in association with the IL SYS INST UM user manual. Make sure you always use the latest documentation – it can be downloaded at [www.sysmik.de](http://www.sysmik.de).

The terminal is designed for use within an Inline station. It is used to output digital signals.

### Features

- Connections for eight digital actuators
- Connection of actuators in 1-wire technology
- Nominal current per output: 0.5 A
- Total current of the terminal: 4 A
- Short-circuit and overload protected outputs
- Diagnostic and status indicators

## 2 Order information

Description	Type	Part number	Pcs./Pkt.
Inline digital output terminal, complete with accessories (connector and labelling field), 8 outputs, 24 V DC, 500 mA, single-wire connection method	ILT 24 DO8/HD	1225-100540-01-3	1
ILT terminals may be replaced by device type 'IB IL' terminals alternatively:	IB IL 24 DO8/HD-PAC	2700172	1

### 3 Technical data

General data	
Housing dimensions (width x height x depth)	12,2 mm x 119,8 mm x 71,5 mm
Weight	60 g (without connectors)
Operating mode	Process data mode with one byte
Ambient temperature (operation)	-25 °C to +55 °C (-13 °F to +13 °F)
Ambient temperature (storage / transport)	-25 °C to +85 °C (-13 °F to +185 °F)
Permissible humidity (operation/storage/transport)	10 % ... 95 % (according to DIN EN 61131-2)
Permissible air pressure (operation/ storage/transport)	70 kPa to 106 kPa (up to 3000 m [9843 ft.] above sea level)
Degree of protection	IP20
Class of protection	III, IEC 61140, EN 61140, VDE 0140-1

Power consumption	
Segment supply voltage $U_S$	24 V DC (nominal value)
Current consumption from $U_S$	max. 4 A DC
Communications power $U_L$	7,5 V DC
Current consumption from $U_L$	max. 45 mA
Power consumption	max. 0,34 W (at $U_L$ )
Power loss	max. 0,62 W

Connection data	
Name	Inline connectors
Connection method	Spring-cage connection
Conductor cross section solid / stranded	0,08 mm <sup>2</sup> ... 1,5 mm <sup>2</sup>
Conductor cross section [AWG]	28 ... 16

Interface	
Local bus	Inline data jumper
Local bus transmission speed	500 kBit/s

Digital outputs	
Number	8
Connection method	Spring-cage connection
Connectioin technology	1-wire
Ausgangsspannung	24 V ( $U_S - 1$ V)
Maximum output current per channel	500 mA
Maximum output current per device	4 A

<b>Digital outputs (continued)</b>	
Nominal load, ohmic	12 W (48 $\Omega$ )
Nominal load, inductive	12 VA (1,2 H; 50 $\Omega$ )
Nominal load, lamp	12 W
Signal delay when switching on an ohmic nominal load	typ. 500 $\mu$ s
Signal delay when switching on an inductive nominal load	typ. 100 ms (1,2 H; 50 $\Omega$ )
Signal delay when switching on a lamp nominal load	typ. 100 ms
Signal delay when switching off an ohmic nominal load	typ. 1 ms
Signal delay when switching off an inductive nominal load	typ. 50 ms (1,2 H; 50 $\Omega$ )
Signal delay when switching off a lamp nominal load	typ. 1 ms
Maximum operating frequency with ohmic nominal load	max. 300 Hz (this switching frequency is limited by the data rate selected, the number of bus devices, the structure of the bus, the software used and the control or computer system used)
Maximum operating frequency with inductive nominal load	max. 0,5 Hz
Maximum operating frequency with lamp nominal load	max. 8 Hz (this switching frequency is limited by the data rate selected, the number of bus devices, the structure of the bus, the software used and the control or computer system used)
Reaction time with short-circuit	ca. 1 s
Reaction time with ohmic overload	ca. 3 s
Behavior at voltage switch-off	The output follows the power supply without delay
One-time unsolicited energy	300 mJ
Limitation of the voltage induced on circuit interruption	$-15 \text{ V} \leq U_{\text{Demag}} \leq -45,8 \text{ V}$ ( $U_{\text{Demag}}$ = demagnetization voltage)
Output voltage when switched off	max. 1 V
Output current when switched off	max. 300 $\mu$ A
Behavior with overload	Auto restart
Restart frequency with ohmic overload	400 Hz
Restart frequency with lamp overload	400 Hz
Behavior with inductive overload	Output can be destroyed
Reverse voltage resistance to short pulses	Reverse voltage proof
Resistance to permanent reverse voltage	max. 500 mA
Overcurrent shut-down	min. 0,7 A
Overload protection, short-circuit protection of outputs	Zener diode in output chip

### Error messages to the higher level control or computer system

Short-circuit / overload of the digital outputs	Error message in the diagnostic code (bus) and display (2 Hz) via the LED (D) on the module
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### Electrical isolation / isolation of the voltage areas



**Note:** To achieve electrical isolation between the logic level and the I/O area, supply these areas from separate power supply units. Interconnection of the power supply units in the 24 V area is not permitted (see also user manual).

5 V supply incoming remote bus / 7.5 V supply (bus logic)	500 V AC, 50 Hz, 1 min.
5 V supply outgoing remote bus / 7.5 V supply (bus logic)	500 V AC, 50 Hz, 1 min.
7.5 V supply (bus logics) / 24 V supply (I/O)	500 V AC, 50 Hz, 1 min.
24 V supply (I/O) / functional earth ground	500 V AC, 50 Hz, 1 min.

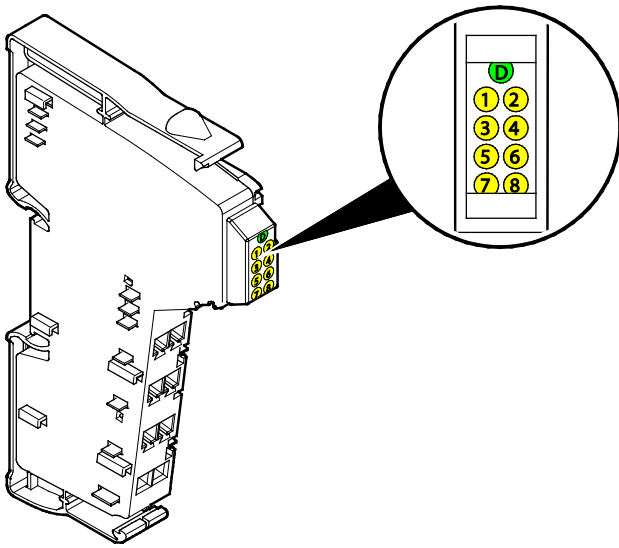
### Approvals

For the latest approvals please visit [www.sysmik.de](http://www.sysmik.de).

### Output characteristic curve when switched on (typical)

Output current (A)	Differential output voltage (V)
0	0
0,1	0,02
0,2	0,03
0,3	0,04
0,4	0,06
0,5	0,07

## 4 Local diagnostic and status indicators and terminal point assignment



**Functional identification:** pink

Fig. 1: Local status and diagnostic indicators

Des.	Color	Meaning
D	green	Diagnostics
1, to 8	yellow	Status of the outputs

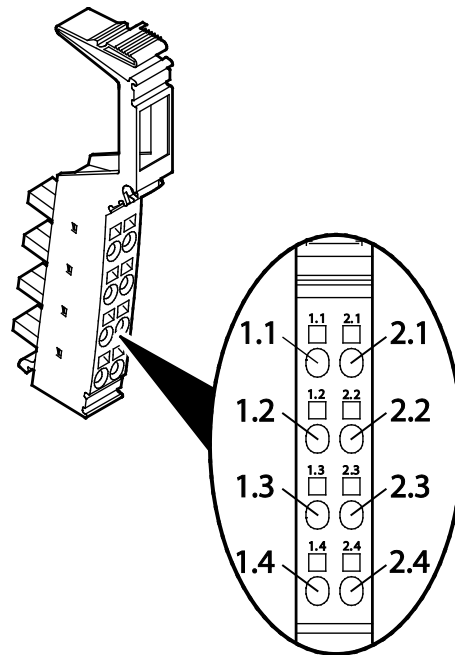


Fig. 2: Terminal assignment

Terminal point	Assignment
1.1 / 2.1	Signal output (OUT 1 / OUT 2)
1.2, 2.2	Signal output (OUT 3 / OUT 4)
1.3, 2.3	Signal output (OUT 5 / OUT 6)
1.4, 2.4	Signal output (OUT 7 / OUT 8)

## 5 Internal circuit

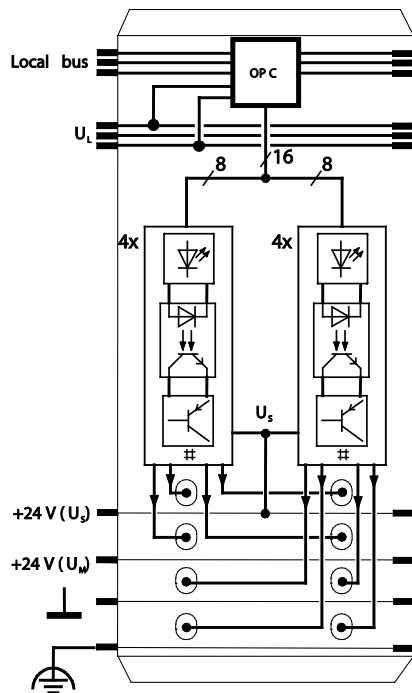


Fig. 3: Interne Beschaltung der Klemmpunkte



Protocol chip (bus logic including voltage conditioning)



LED (status indicator)



Optocoupler



Transistor



Digital output



**Note:** Explanation for other used symbols is provided in the IL SYS INST UM E manual.

## 6 Connection notes and examples


**Note:**

When connecting the actuators, observe the assignment of the terminal points to the process data.


**ATTENTION: Malfunction!**

GND of the actuators and GND of the supply voltage  $U_s$ , which supply the actuators, must have the same potential.

The simplest way to meet this requirement is to use the IB IL PD GND-PAC terminal. Wire the GND connections for the actuators to these terminals. In this way, they are connected with the potential jumper GND of the Inline station.

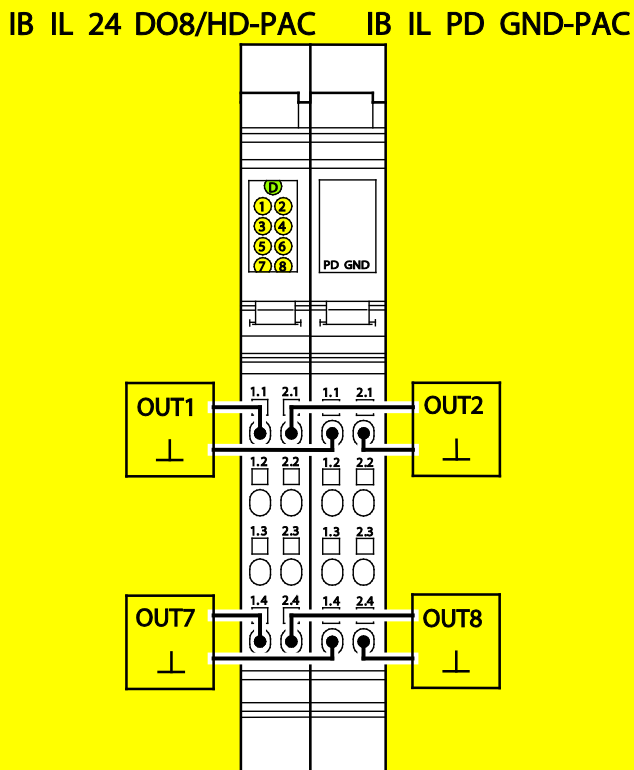


Fig. 4: Typical connection of actuators when using the IB IL PD GND-PAC terminal

The actuators can also be connected via external busbars. Ensure that GND of the actuators and GND for  $U_s$  have the same potential.

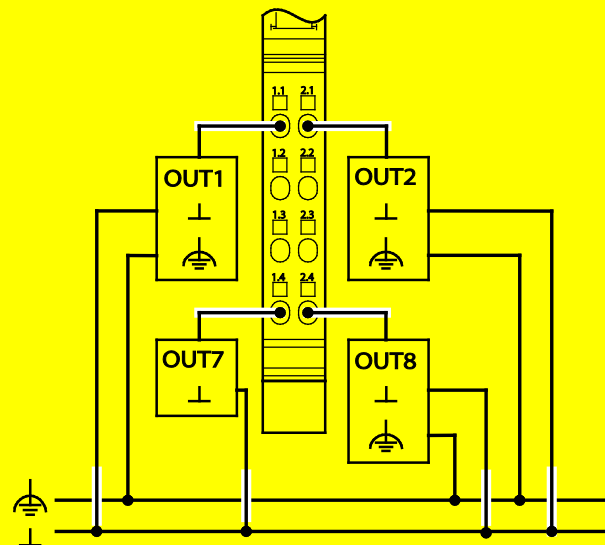


Fig. 5: Typical connection of actuators when using external busbars

## 7 Application examples

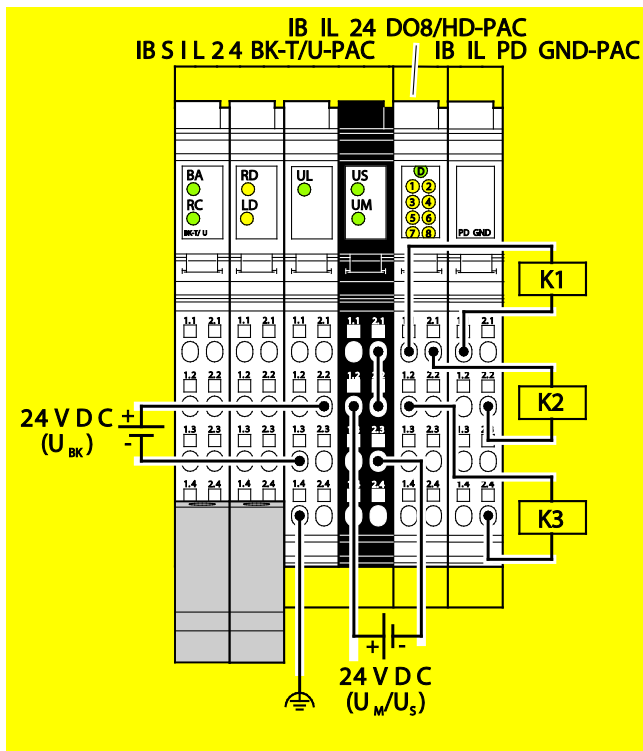


Fig. 6: Connection of contactors when using the IB IL PD GND-PAC terminal

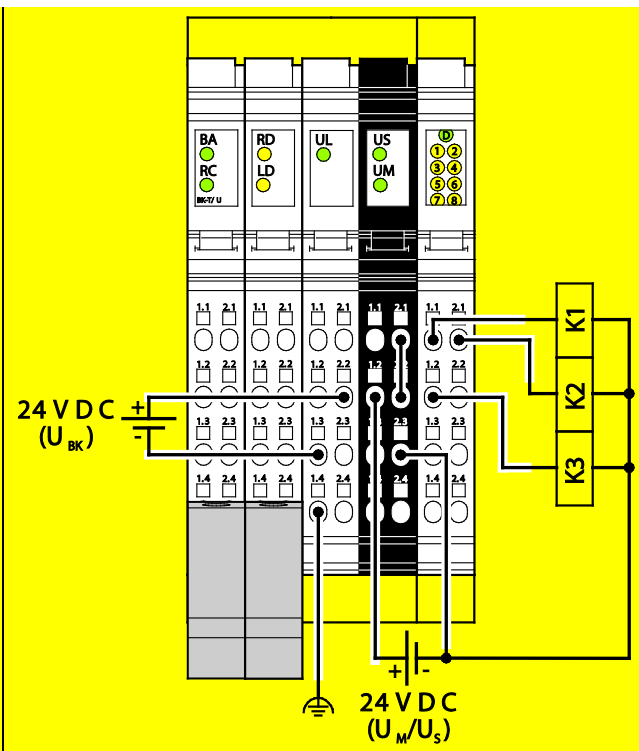


Fig. 7: Connection of contactors when using external busbars